



PROBLEM:

A linear time-invariant system is implemented in MATLAB by the following statement

```
y=filter([1 -2 1],[1 -1.81 .81],x)
```

where x is a vector of input samples.

- (a) Write a MATLAB statement for generating necessary input vector x needed to compute samples of the impulse response $h[n]$ of this system for $0 \leq n \leq 50$.
- (b) What is the system function $H(z)$ of the system?
- (c) Using unit delays, coefficient multipliers, and adders, draw a block diagram of the system whose system function is as determined in part (b).



(a) $x = [1, \text{zeros}(1, 50)];$ OR $nn = 0:50;$
 $h = \text{filter}([1 \ -2 \ 1], [1 \ -1.81 \ .81], x);$ $x = (nn == 0);$

(b)
$$H(z) = \frac{1 - 2z^{-1} + z^{-2}}{1 - 1.81z^{-1} + .81z^{-2}}$$

Use filter coeffs
from b & a vectors

(c) Use Direct Form II

