## **PROBLEM:**

A causal LTI system has the following system function:

$$H(z) = \frac{1 + z^{-2}}{1 - 0.8z^{-1}}.$$

The following questions cover most of the ways available for analyzing IIR discrete-time systems.

- (a) Plot the poles and zeros of H(z) in the z-plane.
- (b) Determine the difference equation that is satisfied by the general input x[n] and the corresponding output y[n] of the system.
- (c) Use inverse *z*-transforms to determine the impulse response h[n] of the system; i.e., the output of the system when the input is  $x[n] = \delta[n]$ .
- (d) Determine if the system is stable.
- (e) Determine an expression for the frequency response  $H(e^{j\hat{\omega}})$  of the system.
- (f) Use the frequency response function to determine the output  $y_1[n]$  of the system when the input is

$$x_1[n] = 2\cos(0.5\pi n) \qquad -\infty < n < \infty.$$



$$H(z) = \frac{1 + z^{-2}}{1 - 0.8z^{-1}}$$
(a)  $H(z) = \frac{z^{2} + 1}{z [z - 0.8]}$ 
  
Zeros:  $z^{2} + 1 = 0 = z^{2} = -1 = e^{j\pi} = e^{j(\pi + 2\pi m)} = z^{2}$ 

$$Z_{m} = e^{j\frac{\pi + 2\pi m}{2}} = m = 0, 1$$

$$Z_{0} = e^{j\pi/2} = j$$

$$Z_{0} = e^{j\frac{3\pi}{2}} = j$$

Poles: 2[2-0.8]=0=) 2=0 & 2=0.8





y(n) = 0.8 y(n-1) + x(n) + x(n-2)

(c) 
$$H(Z) = \frac{1+Z^{-2}}{1-0.8Z^{-1}} = \frac{1}{1-0.8Z^{-1}} + \frac{Z^{-2}}{1-0.8Z^{-1}}$$

$$\frac{2^{-1}\left\{\frac{1}{1-0.8z^{-1}}\right\}}{2^{-1}\left\{\frac{2^{-2}}{1-0.8z^{-1}}\right\}} = 0.8^{n}u(n)$$

$$h(n) = 0.8^{n} u(n) + 0.8^{n-2} u(n-2)$$

(d) Poles are O, and 0.8 inside the unit circle ~ system is stable.

(e) 
$$H(e^{j\hat{\omega}}) = H(z) = \frac{1 + e^{-j2\hat{\omega}}}{1 - 0.8e^{-j\hat{\omega}}}$$

(f) 
$$y_1(n) = H(e^{j(\hat{\omega} = \pi/2)}) \times_1(n)$$

$$H(e^{j(\pi/2)}) = \frac{1 + e^{-j2\pi/2}}{1 - 0.8e^{-j\pi/2}} = 0$$

( ŵ= T/2 zero of H )

Therefore y (n) = 0 for all n.