

Consider the input signal x(t) and the impulse response h(t) shown above. The output of an LTI system is  $y(t) = x(t) * h(t) = \int_{-\infty}^{\infty} x(\tau)h(t-\tau)d\tau$ .

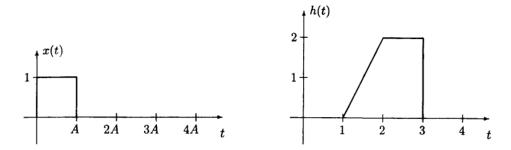
(a) Sketch  $h(2 - \tau)$  as a function of  $\tau$  in the space below.

- (b) If A = 1, for which value(s) of t does y(t) = 1?
- (c) If  $A = \frac{1}{2}$ , what is the maximum value for y(t)? For which value(s) of t does y(t) reach this maximum value?
- (d) What positive value(s) of A will result in the largest maximum value of y(t)? Given these value(s) for A, which value(s) of t does y(t) reach this maximum value?

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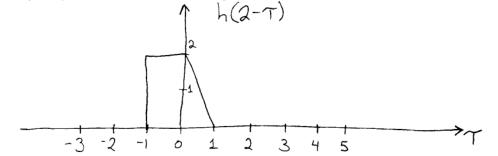




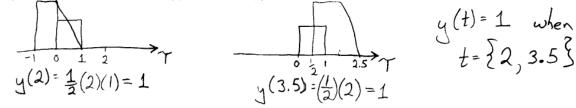


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(a) Sketch  $h(2-\tau)$  as a function of  $\tau$  in the space below.



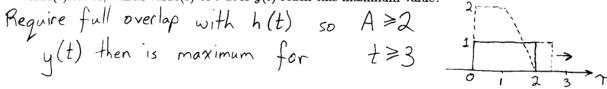
(b) If A = 1, for which value(s) of t does y(t) = 1?



(c) If  $A = \frac{1}{2}$ , what is the maximum value for y(t)? For which value(s) of t does y(t) reach this maximum value?

Maximum value of 
$$y(t) = 2(\frac{1}{2}) = 1$$
  
over the range of  $2.5 \le t \le 3$ .

(d) What positive value(s) of A will result in the largest maximum value of y(t)? Given these value(s) for A, which value(s) of t does y(t) reach this maximum value?



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